Implementing Interaction Techniques



(structure and 2D content based on CS4470/6456 slides by Keith Edwards)

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Recap: Interaction techniques

- A method for carrying out a specific interactive task
 - Example: enter a number in a range
 - could use... (simulated) slider
 - (simulated) knob
 - type in a number (text edit box)
 - Each is a different interaction technique

Suppose we wanted to implement an interaction for specifying a line



- Could just specify two endpoints
 - click, click
 - not good: no affordance, no feedback
- Better feedback is to use "rubber banding"
 - stretch out the line as you drag
 - at all times, shows where you would end up if you "let go"



Aside

- Rubber banding provides good feedback
- How would we provide better affordance?



Aside

- Rubber banding provides good feedback
- How would we provide better affordance?
 - Changing cursor shape is about all we have to work with



Implementing rubber banding

```
Accept the press for endpoint pl;
P2 = P1;
Draw line P1-P2;
Repeat
  Erase line P1-P2;
  P2 = current position();
  Draw line P1-P2;
Until release event;
Act on line input;
```



Implementing rubber banding

- Need to get around this loop absolute min of 5 times / sec
 - I0 times better
 - more would be better
- Notice we need "undraw" here



What's wrong with this code?

```
Accept the press for endpoint p1;
P2 = P1;
Draw line P1-P2;
Repeat
  Erase line P1-P2;
  P2 = current position();
  Draw line P1-P2;
Until release event;
Act on line input;
```

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Not event driven

- Not in the basic event / redraw cycle form
 - don't want to mix event and sampled
 - in many systems, can't ignore events for arbitrary lengths of time
- How do we do this in a normal event / redraw loop?

You don't get to write control flow anymore



- Basically have to chop up the actions in the code above and redistribute them in event driven form
 - "event driven control flow"
 - need to maintain "state" (where you are) between events and start up "in the state" you were in when you left off

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Finite state machine controllers

- One good way to maintain "state" is to use a state machine
 - (deterministic) finite state machine
 - FSM

FSM notation

- Circles represent states
 - arrow for start state
 - double circles for "final states"



- notion of final state is a little off for user interfaces (don't ever end)
- but still use this for completed actions
- generally reset to the start state

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FSM notation

- Transitions represented as arcs
 - Labeled with a "symbol"
 - for us an event (can vary)
 - Also optionally labeled with an action





 Means: when you are in state A and you see a mouse down, do the action (call draw_line), and go to state B



FSM Notation

- Sometimes also put actions on states
 - same as action on all incoming transitions

Rubber banding again (cutting up the code)



Accept the press for endpoint p1; A: |P2 = P1;Draw line P1-P2; Repeat Erase line P1-P2; **B**: P2 = current position(); Draw line P1-P2; Until release event; C: Act on line input;



In a SceneGraph, Lines are Objects

- <u>https://doc.babylonjs.com/snippets/line2d</u>
- Tube as line <u>https://www.babylonjs-playground.com/#MRE78Z</u>
- Recreate each frame
 - https://www.babylonjs-playground.com/#NU4F6Y#242

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Second example: button





FSM for a button?



FSM for a button





A: highlight button B: unhighlight button C: highlight button D: <do nothing> E: do button action



In general...

- Machine states represent context of interaction
 - "where you are" in control flow
- Transitions indicate how to respond to various events
 - what to do in each context



"Events" in FSMs

- What constitutes an "event" varies
 - may be just low level events, or
 - higher level (synthesized) events
 - e.g. region-enter, press-inside

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Guards on transitions

- Sometimes also use "guards"
 - predicate (boolean expression) before event
 - adds extra conditions req to fire
 - typical notation: pred: event / action
 - e.g. button.enabled: press-inside / A

• Note: FSM augmented with guards is Turing complete

FSM are a good way to do control flow in event driven systems



- Can do (formal or informal) analysis
 - are all possible inputs (e.g. errors) handled from each state
 - what are next legal inputs
 - can use to enable / disable
- Can be automated based on higher level specification



Implementing FSMs

state = start_state; for (;;) { raw_evt = wait_for_event(); evt = transform_event(raw_evt); state = fsm_transition(state, evt); }

Note that this is basically the normal event loop



Implementing FSMs

fsm transition(state, evt) switch (state) case 0: // case for each state case 1: // case for next state



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Implementing FSMs
fsm transition(state, evt)
   switch (state)
      case 0: // case for each state
         $witch (evt.kind)
            dase loc move: // trans evt
             ... action ... // trans action
             state = 42; // trans target
            case loc dn:
      case 1: // case for next state
         switch (evt.kind) ...
return state;
```



Table driven implementation

- Very stylized code
- Can be replaced with fixed code + table that represents FSM
 - only have to write the fixed code once
 - can have a tool that generates table from something else



Table driven implementation

- Table consists of array of states
- Each state has list of transitions
- Each transition has
 - event match method
 - list of actions (or action method)
 - target state



Table driven implementation

```
fsm_transition(state, evt)
for each transition TR in table[state]
if TR.match(evt)
TR.action();
state = TR.to_state();
break;
return state
```

Simpler: now just fill in table

Lots of implementations in every language

- Typescript, simple search reveals
 - <u>https://github.com/eram/ts-fsm</u>
 - <u>https://github.com/eonarheim/TypeState</u>
 - https://github.com/raphaelfeng/typescript-state-machine

• ...

Pick one that you feel makes sense!

